

IN THE SPECIFICATION:

Please replace the paragraph beginning at page 3, line 9, with the following rewritten paragraph:

The present invention provides an actuator for a pickup which includes: a fixed portion; a movable portion designed to be movable in each of a focusing direction extending along an optical axis of an objective lens and in a tracking direction substantially perpendicular to the focusing direction, due to a driving force transmitted from a drive portion, for holding the objective lens; and a plurality of linear elastic members of five or more each having ends connected to the movable portion and the fixed portion, respectively. The plurality of the linear elastic members is equal to one another in length dimension between the fixed portion and the movable portion. The ends of the plurality of the linear elastic members are located on a virtual circle formed on a plane by being projected onto a plane including both the focusing direction and the tracking direction. The virtual circle has a center defined as a rolling center $[[,]]$ with which a center of translational forces of the linear elastic members coincides, ~~with at~~ At least one of a center of gravity of the movable portion $[[,]]$ and a center of a driving force of the movable portion, ~~and a center of translational forces of the linear elastic members coincides with the rolling center.~~

Please add the following paragraph after the paragraph beginning at page 3, line 9:

The present invention also provides an actuator for a pickup which includes: a fixed portion; a movable portion designed to be movable in each of a focusing direction extending along an optical axis of an objective lens and a tracking direction substantially perpendicular to the focusing direction, due to a driving force transmitted from a drive portion, for holding the objective lens; and a plurality of linear elastic members of five or more each having ends connected to the movable portion and the fixed portion, respectively. The plurality of the linear elastic members is equal to one another in length dimension between the fixed portion and the movable portion. The ends of the plurality of the linear elastic members are located on a virtual circle formed on a plane by being projected onto a plane including both the focusing direction and the tracking direction. The virtual circle has a center defined as a rolling center, which coincides with a center of translational forces of the linear elastic members, a center of gravity of the movable portion, and a center of a driving force of the movable portion.

Please replace the paragraph beginning at page 4, line 13, with the following rewritten paragraph:

The present invention provides a method of producing an actuator for a pickup including: a fixed portion; a movable portion designed to be movable in each of a focusing direction extending along an optical axis of an objective lens and in a tracking direction substantially perpendicular to the focusing direction, to hold the objective lens; and a plurality of linear elastic members of five or more each having ends connected to the movable portion and the fixed portion, respectively. The

method includes: equalizing the plurality of the linear elastic members to one another in length dimension between the fixed portion and the movable portion; locating the ends of the plurality of the linear elastic members on a virtual circle formed on a plane by being projected onto a plane including both the focusing direction and the tracking direction, respectively; ~~and making at least one of a center of gravity of the movable portion, a center of a driving force of the movable portion, and a center of translational forces of the linear elastic members coincide with a center of the virtual circle defined as a rolling center~~ making a center of translational forces of the linear elastic members coincide with a center of the virtual circle which is defined as a rolling center; and making at least one of a center of gravity of the movable portion and a center of a driving force of the movable portion coincide with the rolling center.

Please replace the paragraph beginning at page 17, line 4, with the following rewritten paragraph:

The line segment linking the suspensions 550A and 550B with each other constitutes the upper base of the trapezoidal shape, and the dimension of a line segment drawn from the rolling center $[[C]]$ Q onto the upper base is denoted by h_2 .

Please replace the paragraph beginning at page 22, line 21, and bridging to page 23, line 3, with the following rewritten paragraph:

Further, in the foregoing respective embodiments of the present invention, the connection portions of the suspensions 550A to 550F are located on the plane including the focusing direction and the tracking direction. However, the present invention also includes cases in which the connection portions of the suspensions 550A to 550F are offset from one another and are not located on the plane. For example, as shown in Fig. 5, the line segments linking the connection portions of the respective suspensions 550A to 550F, which are connected to the lens holder [[12]] 600, with each other do not extend in parallel to the plane of the coil substrate (not shown) mounted to the lens holder 600. Similarly, the line segments linking the connection portions of the respective suspensions 550A to 550F, which are connected to the suspension base 500, with each other do not extend in parallel to the plane of the coil substrate. In Fig. 5, only the suspensions 550A and 550B are illustrated, and the other suspensions 550C to 550F are not illustrated.